ENTROPY COMPUTATION IN PARTIALLY OBSERVED MARKOV CHAINS

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Abstract. Let $X = \{X_n\}_{n \in \mathbb{N}}$ be a hidden process and $Y = \{Y_n\}_{n \in \mathbb{N}}$ be an observed process. We assume that (X,Y) is a (pairwise) Markov Chain (PMC). PMC are more general than Hidden Markov Chains (HMC) and yet enable the development of efficient parameter estimation and Bayesian restoration algorithms. In this paper we propose a fast (i.e., O(N)) algorithm for computing the entropy of $\{X_n\}_{n=0}^N$ given an observation sequence $\{y_n\}_{n=0}^N$.

Keywords: Entropy, Hidden Markov Models, Partially observed Markov Chains

PACS: 05.70.-a, 65.40.Gr, 02.50.-r, 02.50.Ga.

INTRODUCTION

Let $(X,Y) = \{X_n,Y_n\}_{n \in \mathbb{N}}$ be a joint process in which X is unobserved and Y is observed. We assume that X and Y are both discrete with $X_n \in \{1, \dots, K\}$ and $Y_n \in \{1, \dots, M\}$ for all $n \in \mathbb{N}$. Let $X_{i:j} = \{X_n\}_{i \le n \le j}$, $Y_{i:j} = \{Y_n\}_{i \le n \le j}$, $x_{i:j} = \{x_n\}_{i \le n \le j}$ and $y_{i:j} = \{y_n\}_{i \le n \le j}$ (upper case letters denote random variables (r.v.) and lower case letters their realizations). Let also $p(x_{i:j}|y_{i:j})$, say, denote the conditional probability that $X_{i:j} = x_{i:j}$ given $Y_{i:j} = y_{i:j}$. In some applications it is relevant to compute the entropy of $X_{0:N} = \{X_n\}_{n=0}^N$ given an observation $y_{0:N} = \{y_n\}_{n=0}^N$, i.e. we want to compute

$$H(X_{0:N}|y_{0:N}) = -\sum_{x_{0:N}} p(x_{0:N}|y_{0:N}) \log p(x_{0:N}|y_{0:N}).$$
(1)

The brute force computation of (1) requires $O(K^N)$ elementary operations. However, a fast (i.e., $O(K^2N)$) algorithm for computing (1) has been proposed recently [1] in the framework of Hidden Markov Chains (HMC) (see e. g. the recent tutorials [2] [3]), i.e. of processes (X,Y) satisfying

$$p(x_{n+1}|x_{0:n}) = p(x_{n+1}|x_n);$$
 (2)

$$p(y_{0:N}|x_{0:N}) = \prod_{n=0}^{N} p(y_n|x_{0:N});$$
(3)

$$p(y_n|x_{0:N}) = p(y_n|x_n) \text{ for all } n, 0 \le n \le N.$$
(4)

Now, HMC have been generalized recently to Pairwise Markov Chains (PMC) [4], i.e. to joint processes (X,Y) which satisfy

$$p(x_n, y_n | x_{0:n-1}, y_{0:n-1}) = p(x_n, y_n | x_{n-1}, y_{n-1}).$$
(5)

As we see from the definition, a PMC can be seen as a (vector) Markov chain in which one component is observed and the other one is hidden. Now, (2)-(4) imply (5), so any HMC is a PMC. The converse is not true, as can be seen at the local level, since in a PMC the transition probability reads

$$p(x_n, y_n | x_{n-1}, y_{n-1}) = p(x_n | x_{n-1}, y_{n-1}) p(y_n | x_n, x_{n-1}, y_{n-1});$$
(6)

so an HMC is indeed a PMC in which $p(x_n|x_{n-1},y_{n-1})$ reduces to $p(x_n|x_{n-1})$ and $p(y_n|x_n,x_{n-1},y_{n-1})$ reduces to $p(y_n|x_n)$. In other words, making use of PMC enables to model rather complex physical situations, since at time n, conditionnally on the previous state x_{n-1} , the probability of the current state x_n may still depend on the previous observation y_{n-1} ; and conditionnally on x_n , the probability of observation y_n may still depend on the previous state x_{n-1} and on the previous observation y_{n-1} .

It happens that it is possible to extend from HMC to PMC [4] the existing efficient Bayesian restoration or parameter estimation algorithms. As we shall see in this paper, it is also possible in the context of PMC to compute $H(X_{0:N}|y_{0:N})$ efficiently. More precisely, our aim here is to extend to PMC the algorithm of [1]; the algorithm we obtain remains $O(K^2N)$.

EFFICIENT ENTROPY COMPUTATION IN PMC

From now on we assume that (X,Y) is a PMC, i.e. that (5) holds. Let us first recall [5] the following basic properties of entropy:

$$h(U, V/w) = h(U/w) + h(V/U, w),$$
 (7)

$$h(V/U,w) = \sum_{u} h(V/u,w)p(u|w). \tag{8}$$

Let us now address the computation of $H(X_{0:N}|y_{0:N})$. Let $0 \le n \le N$. From (7), (8) we get

$$H(X_{0:n}|y_{0:n}) = H(X_n|y_{0:n}) + H(X_{0:n-1}|X_n, y_{0:n})$$

= $H(X_n|y_{0:n}) + \sum_{x_n} H(X_{0:n-1}|x_n, y_{0:n}) p(x_n|y_{0:n}).$ (9)

On the other hand, from (5) we get

$$p(x_{0:n-2}|x_{n-1},x_n,y_{0:n}) = p(x_{0:n-2}|x_{n-1},y_{0:n-1}),$$
(10)

so $H(X_{0:n-1}|x_n,y_{0:n})$ in (9) can be computed recursively by

$$\begin{split} H(X_{0:n-1}|x_n,y_{0:n}) &= H(X_{n-1}|x_n,y_{0:n}) + H(X_{0:n-2}|X_{n-1},x_n,y_{0:n}) \\ &= H(X_{n-1}|x_n,y_{0:n}) + \sum_{x_{n-1}} H(X_{0:n-2}|x_{n-1},x_n,y_{0:n}) p(x_{n-1}|x_n,y_{0:n}) \\ &\stackrel{(10)}{=} H(X_{n-1}|x_n,y_{0:n}) + \sum_{x_{n-1}} H(X_{0:n-2}|x_{n-1},y_{0:n-1}) p(x_{n-1}|x_n,y_{0:n}) 11) \end{split}$$

It remains to compute $p(x_n|y_{0:n})$ and $p(x_{n-1}|x_n,y_{0:n})$ efficiently. This can be performed by an algorithm which extends to PMC [4] the (forward pass of) the Forward-Backward algorithm [6] [7] [8] [9], and which we now recall

$$p(x_{n-1},x_n|y_{0:n}) = \frac{p(x_{n-1},x_n,y_{0:n})}{\sum_{x_{n-1},x_n}p(x_{n-1},x_n,y_{0:n})}$$

$$\stackrel{(5)}{=} \frac{p(x_n,y_n|x_{n-1},y_{n-1})p(x_{n-1}|y_{0:n-1})p(y_{0:n-1})}{\sum_{x_{n-1},x_n}p(x_n,y_n|x_{n-1},y_{n-1})p(x_{n-1}|y_{0:n-1})p(y_{0:n-1})}$$

$$= \frac{p(x_n,y_n|x_{n-1},y_{n-1})p(x_{n-1}|y_{0:n-1})}{\sum_{x_{n-1},x_n}p(x_n,y_n|x_{n-1},y_{n-1})p(x_{n-1}|y_{0:n-1})}, \qquad (12)$$

$$p(x_n|y_{0:n}) = \sum_{x_{n-1}}p(x_{n-1},x_n|y_{0:n}), \qquad (13)$$

$$p(x_{n-1}|x_n,y_{0:n}) = \frac{p(x_{n-1},x_n|y_{0:n})}{p(x_n|y_{0:n})}. \qquad (14)$$

Let us summarize the discussion. We got the following algorithm:

Fast algorithm for computing $H(X_{0:N}|y_{0:N})$.

- At time n-1:
 - assume that we have $\{H(X_{0:n-2}|x_{n-1},y_{0:n-1})\}_{x_{n-1}=1}^K$, $\{p(x_{n-1}|y_{0:n-1})\}_{x_{n-1}=1}^K$.
- Iteration $n-1 \rightarrow n$:
 - compute $\{p(x_n|y_{0:n})\}_{x_n=1}^K$ and $\{p(x_{n-1}|x_n,y_{0:n})\}_{x_{n-1},x_n=1}^K$ via (12), (13) and (14);
 - compute $\{H(X_{n-1}|x_n, y_{0:n}) = -\sum_{x_{n-1}} p(x_{n-1}|x_n, y_{0:n}) \log p(x_{n-1}|x_n, y_{0:n})\}_{x_n=1}^K$;
 - compute $\{H(X_{0:n-1}|x_n,y_{0:n})\}_{x_n=1}^K$ via (11);
 - compute $H(X_n|y_{0:n}) = -\sum_{x_n} p(x_n|y_{0:n}) \log p(x_n|y_{0:n});$
 - compute $H(X_{0:n}|y_{0:n})$ via (9).

Note that the algorithm is $O(K^2N)$, as was the original algorithm of [1]. Finally, we assumed that Y_n is a discrete r.v., but the extension to continuous emission probability densities is straightforward.

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