

International Workshop on Bayesian Inference and
Maximum Entropy Methods in Science and Engineering

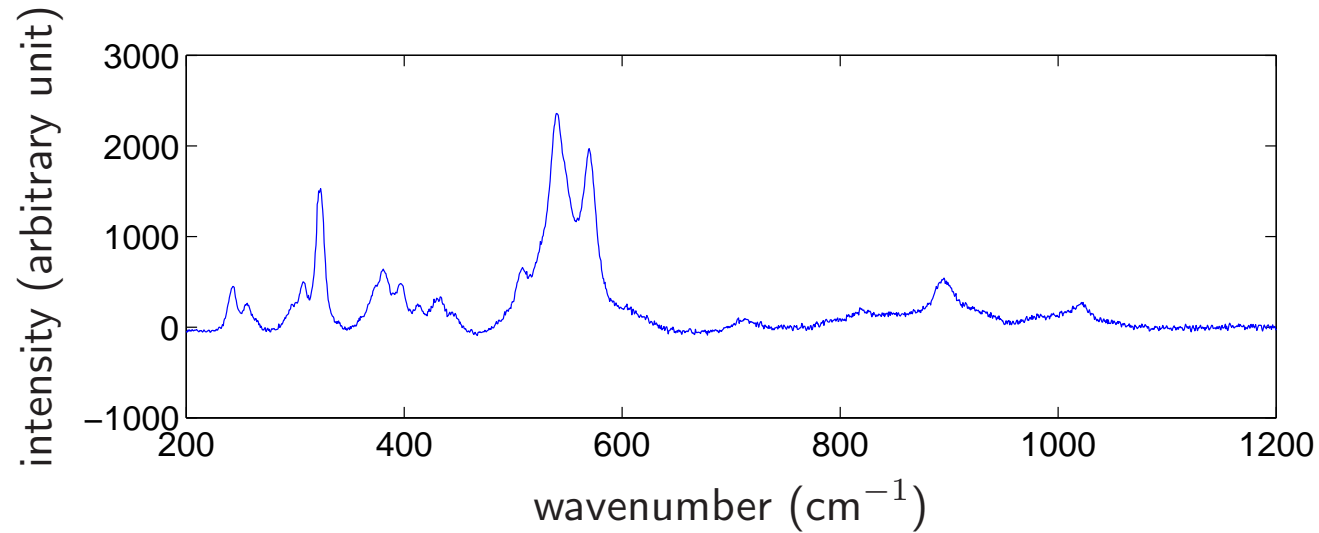
DECOMPOSITION OF A CHEMICAL SPECTRUM USING A MARKED POINT PROCESS AND A CONSTANT DIMENSION MODEL

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Introduction



Goal: estimating the peak parameters (locations, amplitudes and widths) in a spectrum.

→ Provide an interpretation for physico-chemists.

→ Bayesian approach + MCMC method.

Summary

Introduction

1. Problem Formulation

2. Model Definition

- A Constant Dimension Model
- Prior Distributions
- Conditional Posterior Distributions
- Peak Location Simulation

3. Label Switching

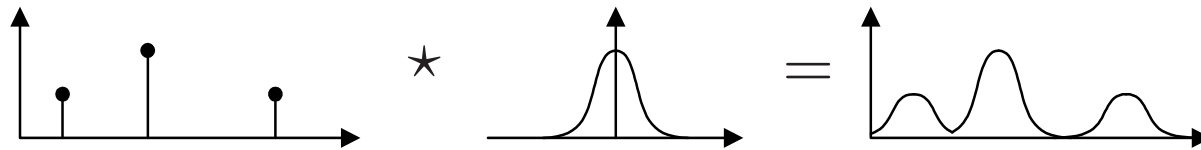
4. Application

Conclusion

1. Problem Formulation

Marked point process: finite set of objects lying in a bounded space and characterized by their locations and some marks.

→ Blind sparse spike train deconvolution

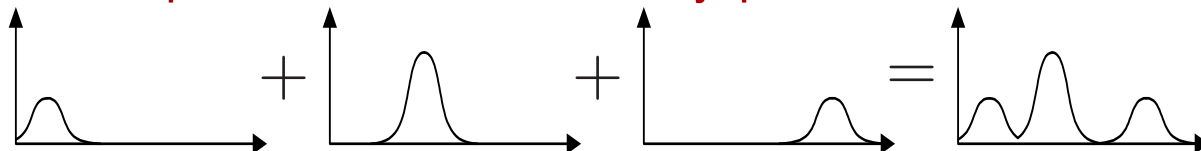


→ **Bernoulli-Gaussian process** (widespread model for sparse spike trains)

Drawbacks:

- common implementation with MCMC methods not efficient
- peaks located on discrete positions
- one peak shape

→ Decomposition into elementary patterns



$$\rightarrow \mathbf{y} = \sum_{k=1}^K \mathbf{f}(\mathbf{n}_k, \mathbf{w}_k, \mathbf{s}_k) + \mathbf{e}$$

2. Proposed Model

2.1 A Constant Dimension Model

$$\mathbf{y} = \sum_{k=1}^K \mathbf{f}(\mathbf{n}_k, \mathbf{w}_k, \mathbf{s}_k) + \mathbf{e}$$

Problem: peak number unknown
 \Rightarrow system order likely to change!

→ MCMC techniques for model uncertainty (RJMCMC algorithm, ...)

→ Constant Dimension Model

peak number equals to constant K_{\max} (upper bound fixed by the user).

Bernoulli-Gaussian model $\rightarrow \mathbf{q} \sim \mathcal{Ber}(\lambda)$ codes the peak occurrences:

- $\mathbf{q}_k = 1$: the k th peak is present (at \mathbf{n}_k with amplitude \mathbf{w}_k and width \mathbf{s}_k)
- $\mathbf{q}_k = 0$: the k th peak is not present

$$\Rightarrow \mathbf{y} = \sum_{k=1}^{K_{\max}} \mathbf{f}(\mathbf{n}_k, \mathbf{w}_k, \mathbf{s}_k) + \mathbf{e}$$

→ variable number smaller than a common BG implementation ($3K_{\max}$ vs. N).

→ allows to use Gibbs sampler

2. Proposed Model

2.2 Prior distributions

Noise:

white, Gaussian and i.i.d.

$$\mathbf{e} \sim \mathcal{N}(\mathbf{0}, r_e \mathbf{I})$$

Peak Location:

uniformly distributed on $[1, N]$

$$\mathbf{n}_k \sim \mathcal{U}_{[1, N]}$$

Peak Amplitude:

BG process + positive amplitudes

$$\mathbf{q}_k \sim \text{Ber}(\lambda)$$
$$\mathbf{w}_k | \mathbf{q}_k \sim \begin{cases} \delta_0(\mathbf{w}_k) & \text{if } \mathbf{q}_k = 0 \\ \mathcal{N}^+(0, r_w) & \text{if } \mathbf{q}_k = 1 \end{cases}$$

Peak Width:

inverse gamma with mean 6 cm^{-1}
and variance 2.5 cm^{-1}

$$\mathbf{s}_k \sim \mathcal{IG}(\alpha_s, \beta_s)$$

2. Proposed Model

2.2 Prior distributions

→ Hyperparameters:

Bernoulli parameter:

conjugate prior to penalize high values

$$\lambda \sim \mathcal{Be}(1, K_{\max} + 1)$$

Peak Amplitude Variance:

conjugate prior less informative as possible

$$r_{\mathbf{w}} \sim \mathcal{IG}(\alpha_{\mathbf{w}}, \beta_{\mathbf{w}})$$

Noise variance:

Jeffreys prior

$$r_{\mathbf{e}} \sim 1/r_{\mathbf{e}}$$

2. Proposed Model

2.3 Conditional Posterior distributions

Peak Location: $\mathbf{n}_k | \dots \sim \exp \left(-\frac{1}{2r_e} \left\| \mathbf{y} - \sum_{l=1}^{K_{\max}} \mathbf{f}(\mathbf{n}_l, \mathbf{w}_l, \mathbf{s}_l) \right\|^2 \right) \mathbb{1}_{[1, N]}(\mathbf{n}_k)$

Peak Amplitude: $\mathbf{q}_k | \dots \sim \text{Ber}(\lambda_k)$

$$\mathbf{w}_k | \dots \sim \begin{cases} \delta_0(\mathbf{w}_k) & \text{if } \mathbf{q}_k = 0 \\ \mathcal{N}^+(\mu_k, \rho_k) & \text{if } \mathbf{q}_k = 1 \end{cases}$$

Peak Width: $\mathbf{s}_k | \dots \sim \exp \left(-\frac{1}{2r_e} \left\| \mathbf{y} - \sum_{l=1}^{K_{\max}} \mathbf{f}(\mathbf{n}_l, \mathbf{w}_l, \mathbf{s}_l) \right\|^2 - \frac{\beta_s}{s_k} \right) \frac{1}{s_k^{\alpha_s+1}} \mathbb{1}_{\mathbb{R}^+}(\mathbf{s}_k)$

Bernoulli parameter: $\lambda | \dots \sim \text{Be}(K+1, 2K_{\max} - K + 1)$

Peak Amplitude Variance: $r_{\mathbf{w}} | \dots \sim \mathcal{IG} \left(\frac{K}{2} + \alpha_{\mathbf{w}}, \frac{\mathbf{w}^T \mathbf{w}}{2} + \beta_{\mathbf{w}} \right)$

Noise variance: $r_e | \dots \sim \mathcal{IG} \left(\frac{N}{2}, \frac{1}{2} \left\| \mathbf{y} - \sum_{l=1}^{K_{\max}} \mathbf{f}(\mathbf{n}_l, \mathbf{w}_l, \mathbf{s}_l) \right\|^2 \right)$

2. Proposed Model

2.4 Peak Location Simulation

$$\mathbf{n}_k | \dots \sim \exp \left(-\frac{1}{2r_e} \left\| \mathbf{y} - \sum_{l=1}^{K_{\max}} \mathbf{f}(\mathbf{n}_l, \mathbf{w}_l, \mathbf{s}_l) \right\|^2 \right) \mathbb{1}_{[1,N]}(\mathbf{n}_k)$$

Metropolis-Hastings algorithm \rightarrow which proposal distribution?

\rightarrow If the peak is present ($\mathbf{q}_k = 1$)

define precisely its location: $\mathcal{N}^{[1,N]}(\mathbf{n}_k^{(i-1)}, r_{\mathbf{n}})$

\rightarrow If the peak is absent ($\mathbf{q}_k = 0$)

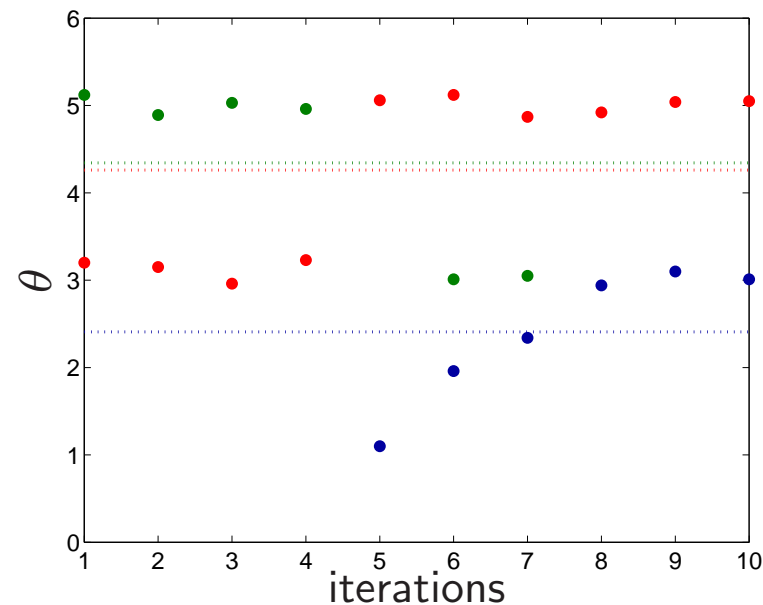
explore the entire space: $\mathcal{U}_{[1,N]}$

$$\Rightarrow q(\tilde{\mathbf{n}}_k) = \delta_0(\mathbf{q}_k) \mathcal{U}_{[1,N]} + \delta_1(\mathbf{q}_k) \mathcal{N}^{[1,N]}(\mathbf{n}_k^{(i-1)}, r_{\mathbf{n}}).$$

3. Label Switching

The label switching problem is due to 2 phenomena:

- same posterior for all permutation of k : $p(\theta_1, \theta_2, \theta_3 | \mathbf{y}) = p(\theta_2, \theta_3, \theta_1 | \mathbf{y})$
- Gibbs sampler able to explore the $k!$ permutation possibilities



$$\hat{\theta}_1 = 4.26, \quad \hat{\theta}_2 = 4.34, \quad \hat{\theta}_3 = 2.41$$

3. Label Switching

Proposed Method

Minimizing the following cost function (see [Stephens 1997]):

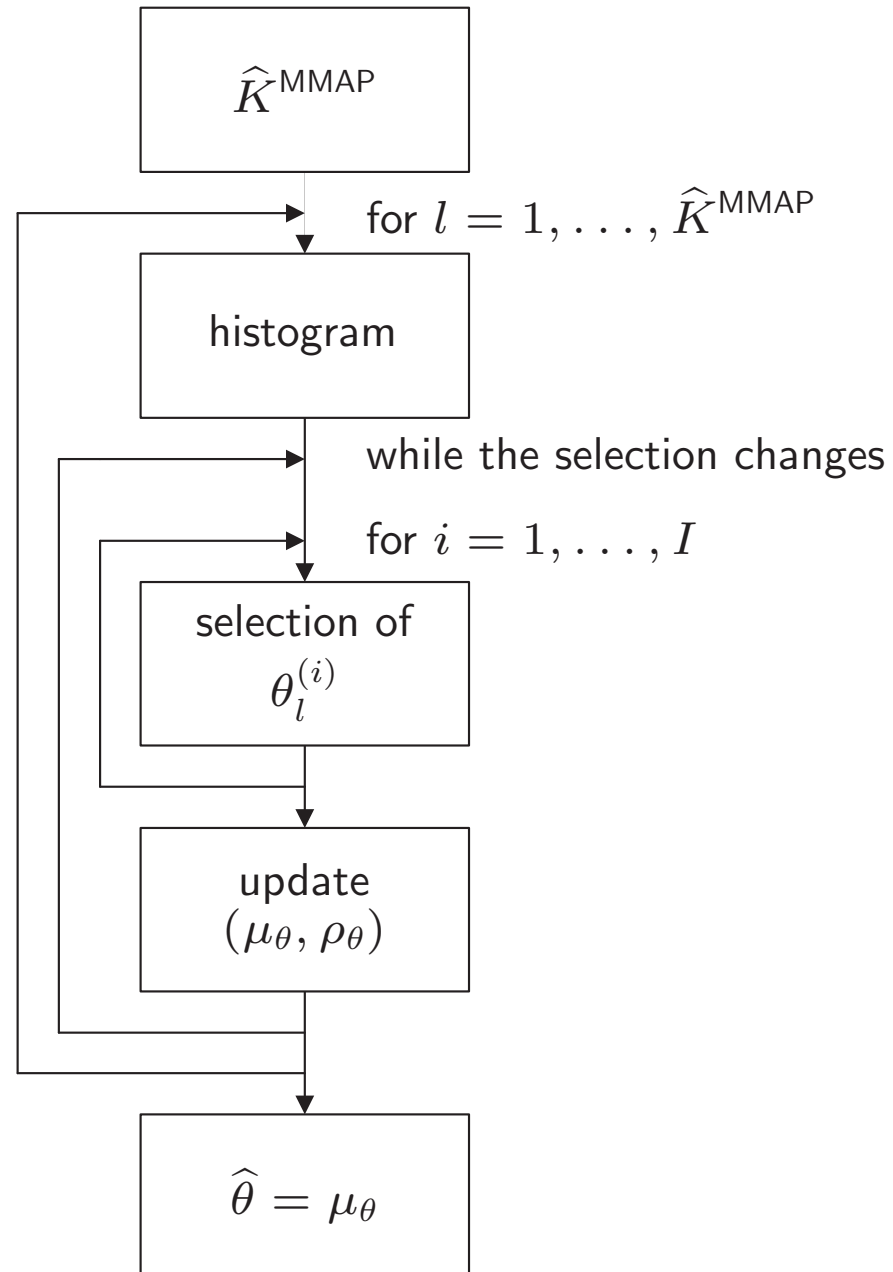
$$\mathcal{L}_0(\mathbf{n}, \mathbf{w}, \mathbf{s}, \mu_{\mathbf{n}}, \rho_{\mathbf{n}}, \mu_{\mathbf{w}}, \rho_{\mathbf{w}}, \mu_{\mathbf{s}}, \rho_{\mathbf{s}}) = -\ln \left[\prod_{k=1}^{K_{\max}} \mathcal{N}(\mathbf{n}_k | \mu_{\mathbf{n}_k}, \rho_{\mathbf{n}_k}) \mathcal{N}(\mathbf{w}_k | \mu_{\mathbf{w}_k}, \rho_{\mathbf{w}_k}) \mathcal{N}(\mathbf{s}_k | \mu_{\mathbf{s}_k}, \rho_{\mathbf{s}_k}) \right]$$

Major differences to general relabelling algorithms:

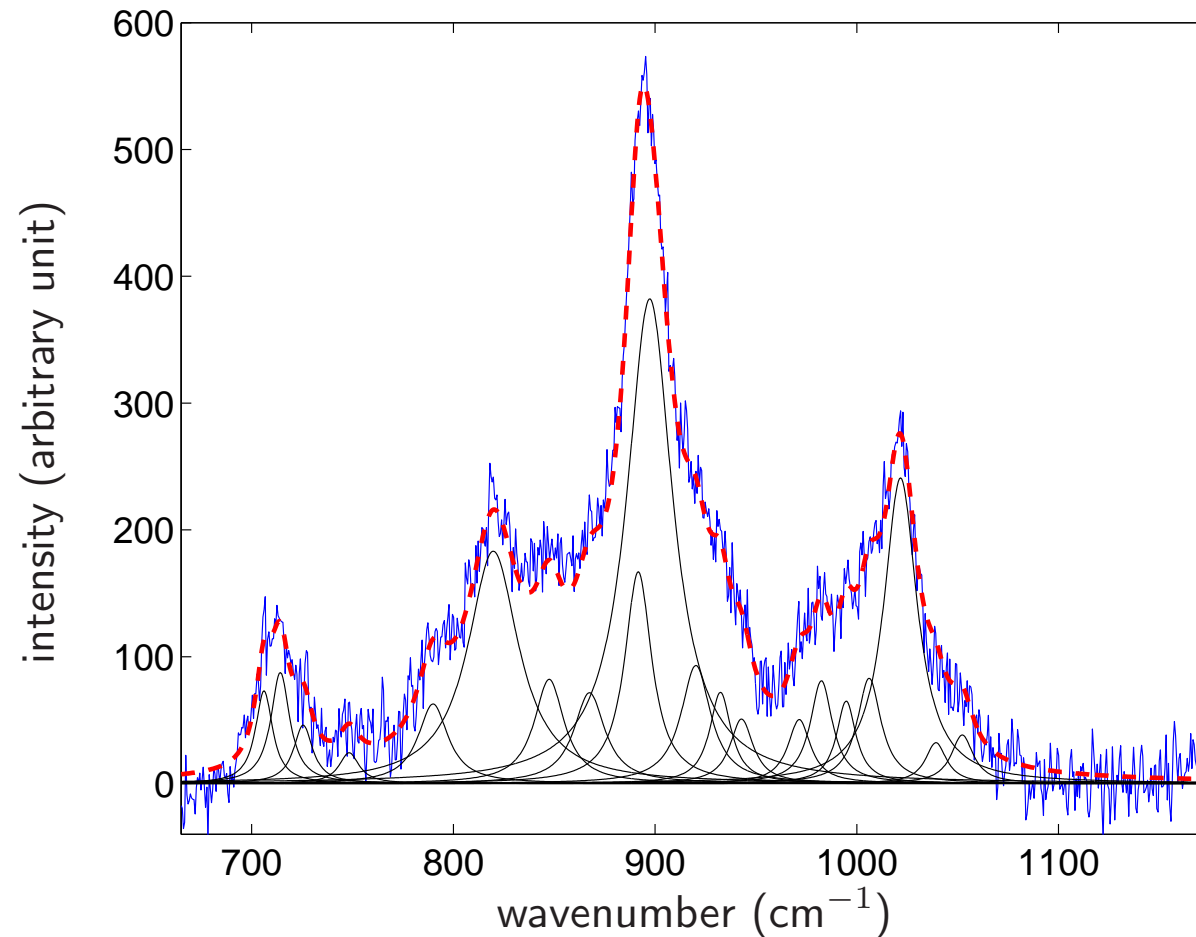
- initialization obtained by selecting the maximum in the histogram of $(\mu_{\mathbf{n}}, \mu_{\mathbf{w}}, \mu_{\mathbf{s}})$ (closer to the global optimum than a simple identity permutation)
- relabelling $(\mathbf{n}_l, \mathbf{w}_l, \mathbf{s}_l)$ one after the other (no permutation)
- taking into account the fact that the peak number is expected to change

3. Label Switching

$$\theta = (\mu_{\mathbf{n}}, \mu_{\mathbf{w}}, \mu_{\mathbf{s}})$$



4. Application



Raman spectrum of gibbsite $\text{Al}(\text{OH})_3$

- 10,000 iterations (burn-in period of 5,000 iterations).
- Initialization: spectrum with no peak, $\lambda^{(0)} = 0.5$, $r_w^{(0)} = 10$, $r_e^{(0)} = 0.1$.

Conclusion

→ Signal decomposition into elementary patterns (marked point process)

Alternative to blind sparse spike train deconvolution

- more efficient than a common implementation with BG model
- peaks located on a continuous space
- peak with different shapes

→ Constant dimension model

Alternative to RJMCMC

→ New method for label switching

- initialization close to the global optimum using an histogram
- relabelling with no permutation
- the variable number may change