

Copula and Tomography

Ali Mohammad-Djafari & Doriano-Boris Pougaza

Groupe Problèmes Inverses
Laboratoire des Signaux et Systèmes
(UMR 8506 CNRS - SUPELEC - Univ Paris Sud 11)
Supélec, Plateau de Moulon, 91192 Gif-sur-Yvette, FRANCE.

djafari@lss.supelec.fr
<http://djafari.free.fr>
<http://www.lss.supelec.fr>

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Content

- ▶ Tomography
- ▶ Radon Transform
- ▶ Classical methods of Tomography
- ▶ Tomography and Copula
- ▶ Some preliminary results
- ▶ Conclusions

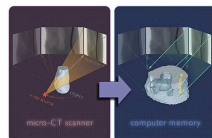
Tomography : seeing interior of a body

- ▶ $f(x, y)$ a section of a real 3D body $f(x, y, z)$
- ▶ $g_\phi(r)$ a line of observed radiographie $g_\phi(r, z)$
- ▶ Forward model :
Line integrals or Radon Transform

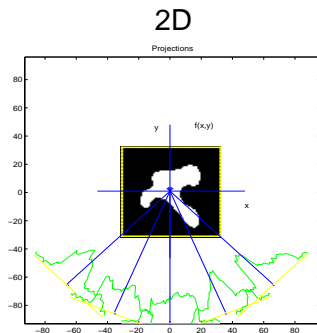
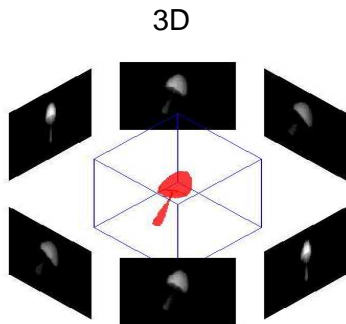
$$\begin{aligned}g_\phi(r) &= \int_{L_{r,\phi}} f(x, y) dl + \epsilon_\phi(r) \\ &= \iint f(x, y) \delta(r - x \cos \phi - y \sin \phi) dx dy + \epsilon_\phi(r)\end{aligned}$$

- ▶ Inverse problem : Image reconstruction

Given the forward model \mathcal{H} (Radon Transform) and
a set of data $g_{\phi_i}(r), i = 1, \dots, M$
find $f(x, y)$



2D and 3D Computed Tomography

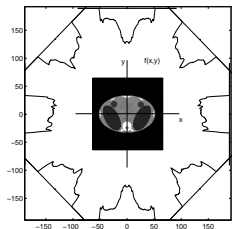


$$g_{\phi}(r_1, r_2) = \int_{\mathcal{L}_{r_1, r_2, \phi}} f(x, y, z) dl \quad g_{\phi}(r) = \int_{\mathcal{L}_{r, \phi}} f(x, y) dl$$

Forward problem : $f(x, y)$ or $f(x, y, z) \longrightarrow g_{\phi}(r)$ or $g_{\phi}(r_1, r_2)$

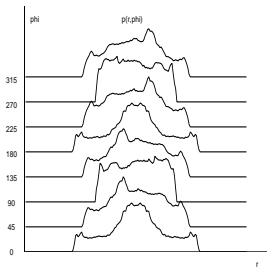
Inverse problem : $g_{\phi}(r)$ or $g_{\phi}(r_1, r_2) \longrightarrow f(x, y)$ or $f(x, y, z)$

X ray Tomography and Radon Transform

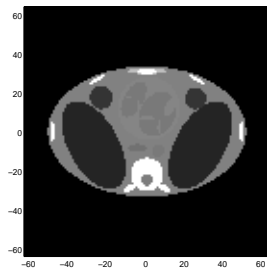


$$g(r, \phi) = -\ln \left(\frac{I}{I_0} \right) = \int_{L_{r, \phi}} f(x, y) dl$$

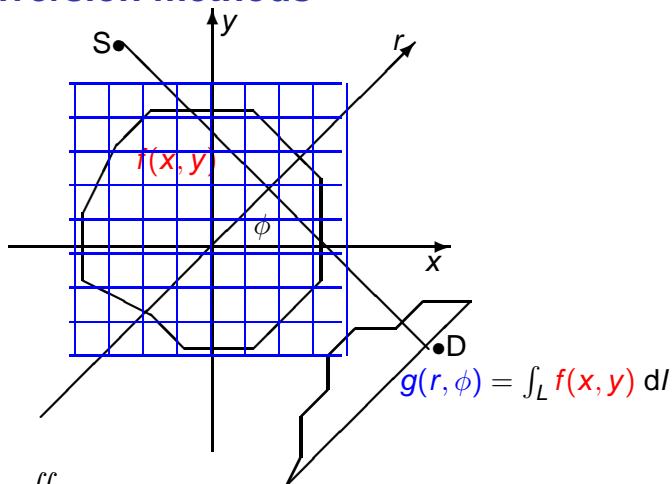
$$g(r, \phi) = \iint_D f(x, y) \delta(r - x \cos \phi - y \sin \phi) dx dy$$



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Analytical Inversion methods



Radon :

$$g(r, \phi) = \iint_D f(x, y) \delta(r - x \cos \phi - y \sin \phi) dx dy$$

$$f(x, y) = \left(-\frac{1}{2\pi^2} \right) \int_0^\pi \int_{-\infty}^{+\infty} \frac{\frac{\partial}{\partial r} g(r, \phi)}{(r - x \cos \phi - y \sin \phi)} dr d\phi$$

Filtered Backprojection method

$$f(x, y) = \left(-\frac{1}{2\pi^2} \right) \int_0^\pi \int_{-\infty}^{+\infty} \frac{\frac{\partial}{\partial r} g(r, \phi)}{(r - x \cos \phi - y \sin \phi)} dr d\phi$$

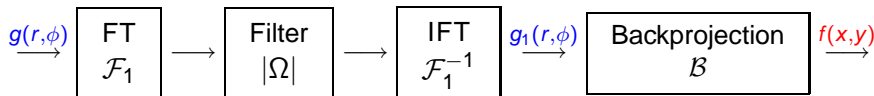
Derivation \mathcal{D} : $\bar{g}(r, \phi) = \frac{\partial g(r, \phi)}{\partial r}$

Hilbert Transform \mathcal{H} : $g_1(r', \phi) = \frac{1}{\pi} \int_0^\infty \frac{\bar{g}(r, \phi)}{(r - r')} dr$

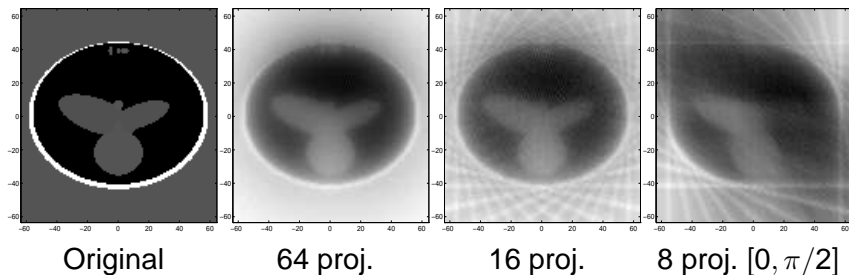
Backprojection \mathcal{B} : $f(x, y) = \frac{1}{2\pi} \int_0^\pi g_1(r' = x \cos \phi + y \sin \phi, \phi) d\phi$

$$f(x, y) = \mathcal{B} \mathcal{H} \mathcal{D} g(r, \phi) = \mathcal{B} \mathcal{F}_1^{-1} |\Omega| \mathcal{F}_1 g(r, \phi)$$

- Backprojection of filtered projections :

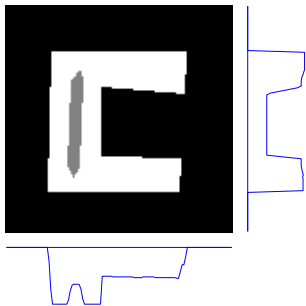


Limitations : Limited angle or noisy data

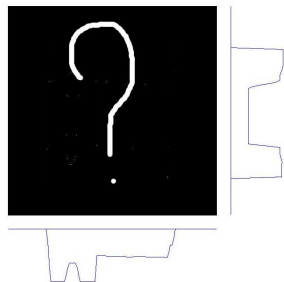


- ▶ Limited angle or noisy data
- ▶ Accounting for detector size
- ▶ Other measurement geometries : fan beam, ...

Tomography with only Two projections



Forward problem :
Given $f(x, y)$ find $f_1(x)$ and $f_2(y)$

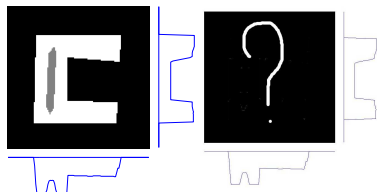


Inverse problem :
Given $f_1(x)$ and $f_2(y)$ find $f(x, y)$

Link between Tomography and Copula

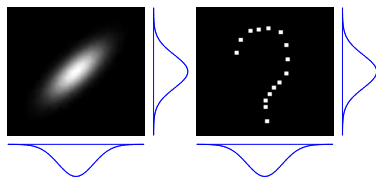
Tomography :

Given the two horizontal
and vertical projections
 $f_1(x)$ and $f_2(y)$,
find $f(x, y)$



Copula :

Given the two marginal
pdfs $f_1(x)$ and $f_2(y)$,
find the joint pdf $f(x, y)$



Ill-posed Inverse problems : Infinite number of solutions

There is a need to reduce the space of possible solutions

Link between Tomography and Copula

Copula and Tomography

Given $f_1(x)$ and $f_2(y)$ find $f(x, y)$ such that

$$f_1(x) = \int f(x, y) dy \quad \text{and} \quad f_2(y) = \int f(x, y) dx$$

Tomography :

If we find a solution $f_0(x, y)$, we can add any function $\omega(x, y)$ such that

$$\int \omega(x, y) dx = \int \omega(x, y) dy = 0$$

and we get again another solution.

Copula :

Any function $f(x, y)$ given by

$$f(x, y) = f_1(x) f_2(y) c(F_1(x), F_2(y))$$

where $c(u, v)$ is any copula, is a solution to the problem.

$$\int c(x, y) dx = \int c(x, y) dy = 1$$

Link between Tomography and Copula

Tomography :

Back Projection (BP) :

$$f(x, y) = f(x) + f(y)$$

Copula :

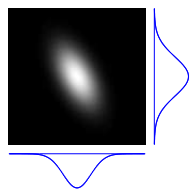
Multiplicative Back Projection (MBP) :

$$f(x, y) = f(x) f(y)$$

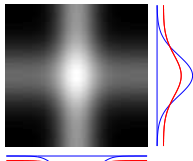
Copula Back Projection (MBP) :

$$f(x, y) = f(x) f(y) c(F_1(x), F_2(y))$$

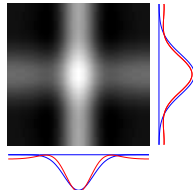
Preliminary results



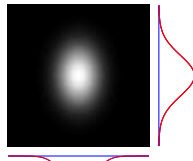
$f(x,y)$, $I_x(x)$ and $I_y(y)$



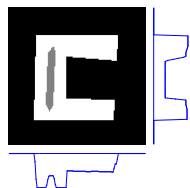
$\hat{f}(x,y)$, $\hat{I}_x(x)$ and $\hat{I}_y(y)$



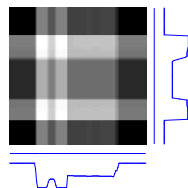
$\hat{f}(x,y)$, $\hat{I}_x(x)$ and $\hat{I}_y(y)$



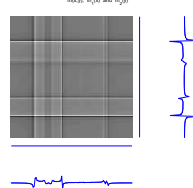
$\hat{f}(x,y)$, $\hat{I}_x(x)$ and $\hat{I}_y(y)$



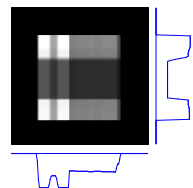
Originals $f(x,y)$



BP $\hat{f}(x,y)$

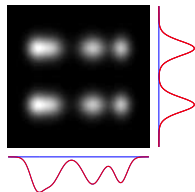
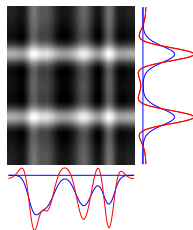
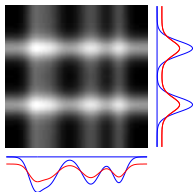
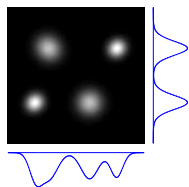
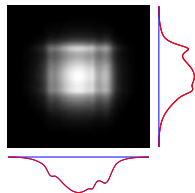
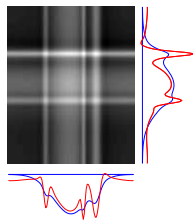
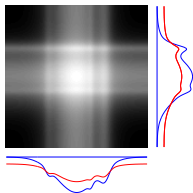
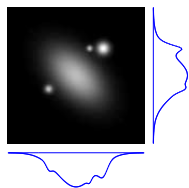


FBP $\hat{f}(x,y)$



MBP $\hat{f}(x,y)$

Preliminary results



Originals $f(x, y)$

BP $\hat{f}(x, y)$

FBP $\hat{f}(x, y)$

MBP $\hat{f}(x, y)$

Conclusions

- ▶ There is a link between Copula and Tomography.
- ▶ Both problems are ill-posed.
- ▶ We are sure that the methods in one domain can be useful in other one.
- ▶ With only two projections we can only reconstruct simple images
- ▶ There is a need for more data or for more constraints (maximum entropy, minimum energy, ...)
- ▶ How to use more than 2 projections with Copula ?